DRAW WIRE SENSOR



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Series SX120

Key-Features:

- Measurement ranges from 3125 to 5000 mm
- Analog Output: Potentiometer, 0...10 V, 4...20 mA
- teachable outputs: 0...5 V, 0...10 V,
 with an additional Open-Collector switching output
- Digital Output Incremental: RS422 (TTL), push-pull
- Digital Output Absolute: CANopen, SSI, Profibus, EtherCAT, Profinet
- Linearity up to ±0.02% of full scale
- Protection class up to IP67
- Temperature range -20...+85 °C (optional -40 °C or +120 °C)
- High dynamics
- High interference immunity factor
- Customised versions available

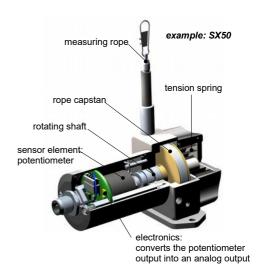


INTRODUCTION

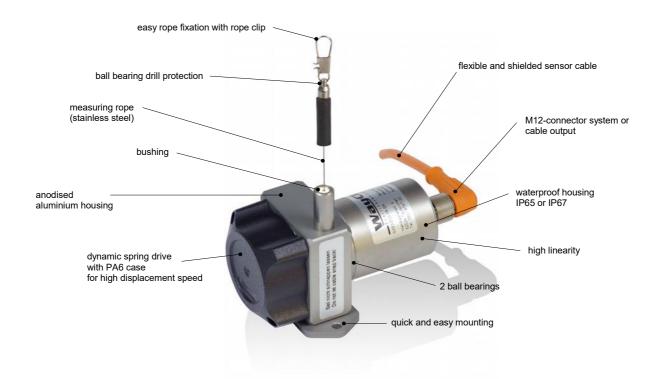
WayCon Positionsmesstechnik GmbH is a manufacturer of high quality draw wire position sensors for industrial use. Due to its small overall size, its short assembly time and its possible customisation, the SX sensor technology is a cost-effective and flexible solution for a wide range of industrial applications. The dynamics of the draw wire transducer allows a high motion speed and acceleration of the measuring target. Its rugged design and high quality makes applications in harsh industrial environments possible. Special instruments are available with mounting service of encoder on site, as well as customised versions of housing.

Sensor principle:

The key component of a draw wire sensor is a highly flexible steel wire rope, that is winded single-layered on an ultra light capstan. This capstan is connected to the sensor housing by a pre-stressed spring. The end of the steel wire rope, that is equipped with a rope clip gets connected to the target object. As soon as the distance between sensor and target object changes, the steel wire rope gets pulled out of the sensor and is rolled off the capstan (or vice versa). The shaft of the capstan is connected to a potentiometer (for analog output signals), or to an encoder (for digital output signals). If there is a rotation of the capstan due to a change in the distance to the target object, the sensor element will turn proportionally. This way the potentiometer, or the encoder converts a linear movement into a proportional electrical signal. If a standard analog output signal, like 0...10 V or 4...20 mA is needed, the sensor is equipped with an additional electronics.



SPECIAL FEATURES



WARNING NOTICES

- Don't let the rope snap back. If the rope is retracted freely, this may lead to injuries (whiplash effect) and the device may be damaged.
 Caution when unhooking and retracting the rope into the sensor.
- Never exceed the specified measurement range when extracting the rope!
- · Do not try to open the device. The stored energy of the spring drive may lead to injuries when being mishandled.
- · Do not touch the rope when operating the sensor.
- · Avoid guiding the rope over edges or corners. Use a deflection pulley instead.
- Do not operate the sensor if the rope is buckled or damaged. A ripping of the rope may lead to injuries or a damaging of the sensor.





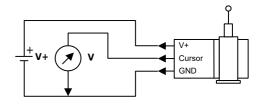
TECHNICAL DATA ANALOG OUTPUT

Measurement range *	[mm]	3125	4000	5000			
Linearity	[%]	0.10	0.10	0.10			
Improved linearity (optional)	[%]	0.05	-	-			
Resolution			see types of output table below				
Sensor element			Hybrid Potentiometer				
Connection		connector output M	112 axial or cable output axial (TPE cable, s	standard length 2 m)			
Protection class		IP65, optional IP67					
Humidity		maximum 90 % relative, no condensation					
Temperature	[°C]	standard: -20+85 / optional: -40+85 / optional: -20+120 °C (only with Potentiometer (1R) and cable output (KA))					
Mechanical data		extraction force, maximum velocity and maximum acceleration see table page 13					
Weight	[9]	300 to 500, depending on the measurement range					
Housing		aluminium, anodised, spring case PA6					
Accessories		cables, connectors, digital display	s, deflection pulley, rope extensions, mag	netic clamp (see pages 11 and 12)			

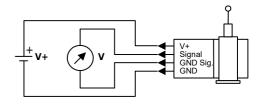
^{*} other ranges on request

TYPES OF ANALOG OUTPUT

Potentiometer (voltage divider)	
Output	1 kΩ
Supply	max. 30 V
Recommended cursor current	< 1 µA
Resolution	theoretically unlimited, limited by the noise
Noise	dependent on the quality of the power supply
Working temperature	-20+85 °C , optional: -40+85 °C / -20+120 °C
Temperature coefficient	± 0.0025 %/K

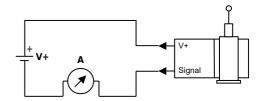


Voltage 010 V	
Output	010 V, galvanically isolated, 4 conductors
Supply	1230 VDC
Current consumption	max. 22.5 mA (unloaded)
Output current	max. 10 mA, min. load 10 kOhm
Dynamics	< 3 ms from 0100 % and 1000 %
Resolution	limited by the noise
Noise	3 mV $_{\rm pp}$ typical, max. 37 mV $_{\rm pp}$
Inverse-polarity protection	yes, infinite
Short-circuit proof	yes, permanent
Working temperature	-20+85 °C , optional: -40+85 °C
Temperature coefficient	0.0037 %/K
Electromagnetic compatibility (EMC)	according to EN 61326-1:2006



Note: GND Sig. and GND may be connected in a 3-wire system.

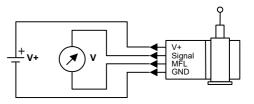
Current 420 mA	
Output	420 mA, 2 conductors
Supply	1230 VDC
Output current	max. 50 mA in case of error
Dynamics	< 1 ms from 0100 % and 1000 %
Resolution	limited by the noise
Noise	$0.03 \text{ mA}_{pp} = 6 \text{ mV}_{pp} \text{ at } 200 \text{ Ohm}$
Inverse-polarity protection	yes, infinite
Working temperature	-20+85 °C , optional: -40+85 °C
Temperature coefficient	0.0079 %/K
Electromagnetic compatibility (EMC)	according to EN 61326-1:2006





TYPES OF ANALOG OUTPUT

Output: Voltage 05 V, 010 V teachable up to approx. 50% of full scale					
Output	05 V, 010 V, 3 wire system				
Supply	835 VDC				
Power consumption	max. 150 mW				
Output current	max. 10 mA, min. load 1 kOhm				
Dynamics	1 ms				
Resolution	1 mV				
Noise	3 mV _{ss} typical, max. 37 mV _{ss}				
Inverse-polarity protection	yes, infinite				
Short-circuit proof	yes, permanent				
Working temperature	-40+85 °C				
Temperature coefficient	0.0016 %/K				
Electromagnetic compatibility (EMC)	according to EN 61326-1:2006				



MFL: Multi-functional line

TEACHABLE OUTPUT 5VT, 10VT, SQUEEZER

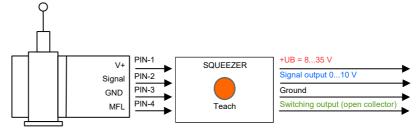
Draw wire sensors with the analogue output versions 5VT and 10 VT are equipped with a teachable, internal electronics, called VT-Electronics. The signals provided by the sensor's potentiometer are digitized by the VT-Electronics. This digital information is first processed by the electronics, then transformed back and given out as an analogue output signal 0 to 10 V or 0 to 5 V.

The digitization offers two possibilities of adjustment, by which the sensor can be configured individually using the squeezer:

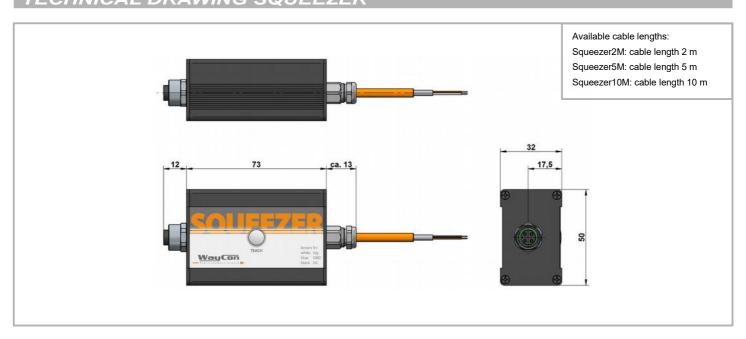
1) Teaching of the measurement range. After a successful teaching process the squeezer can be pulled off the sensor and be replaced by a standard cable or connector.

2) Setting an individual switching point. The squeezer allows the setting of an individual switching point open collector. The switching signal is emitted through the Multi-functional line MFL.

You will find a detailed description of the functions in a separate manual.

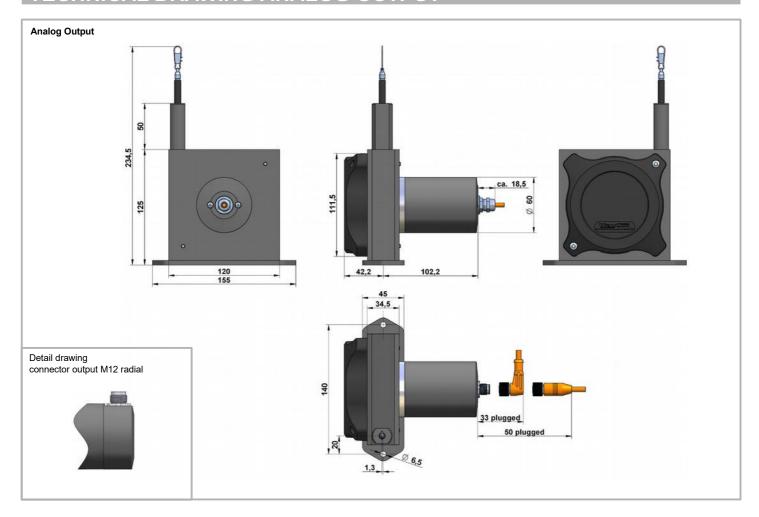


TECHNICAL DRAWING SQUEEZER





TECHNICAL DRAWING ANALOG OUTPUT

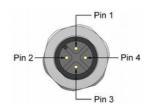


ELECTRICAL CONNECTION ANALOG OUTPUT

Cable output TPE, flexible Cable type Cable direction axial Length standard: 2 m, (others on request) 4.5 mm Diameter 0.25 mm² Wire fixed installation -30...+85 °C, flexible installation -20...+85 °C Temperature 0...5 V, 0...10 V Cable colour 0...10 V 4...20 mA 1 kOhm (teachable) brown ٧+ ۷+ ٧+ white Signal Cursor Signal n. c. GND Signal GND GND GND Signal MFL* black n. c. n. c. * Multi-functional line

Connector output

- M12, 4 poles
- female connector

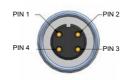


Pin	010 V	420 mA	1 kOhm	05 V, 010 V (teachable)
1	V +	V +	V +	V +
2	Signal	n. c.	Cursor	Signal
3	GND	Signal	GND	GND
4	GND Signal	n. c.	n. c.	MFL

^{*} Multi-functional line

Squeezer for sensors with analogue output 5VT, 10VT

Connection cable sensor - squeezer: K4P1,5M-SB-M12 (accessory)



Connector (to sensor)						
Pin 1	V +					
Pin 2	Signal					
Pin 3	GND					
Pin 4	MFL*					

Pin 3	GND	blue	GND
Pin 4	MFL*	black	NPN**
* multifuctional line		** The Open Collector i	is a NPN switching output

brown white

Cable ends (e.g. to PLC)

V + (8...35 V)

Signal



^{**} The Open Collector is a NPN switching output

TECHNICAL DATA DIGITAL OUTPUT INCREMENTAL

Measurement range *	[mm]	3125 / 4000 / 5000
Linearity	[%]	0.05, independent of the measurement range
Improved linearity (optional)	[%]	0.02, independent of the measurement range, only in combination with resolution 6.3 pulses/mm, or higher
Selectable resolution	[Pulses/mm]	0.3 / 3.1 / 6.3 / 15,7 (this resolution can be raised by the factor 4 using quadruple edge detection)
Z-Pulse distance	[mm]	317.68
Sensor element		Incremental-Encoder (with optical code disk)
Output signal		A/B-Pulses (90° phase-delayed), Z-Pulse (plus inverted pulses A_{not} , B_{not} , Z_{not})
Connection		M12 or M23 connector output or cable output with open ends (standard length 2 m)
Protection class		IP65, optional IP67
Humidity		maximum 90 % relative, no condensation
Temperature range	[°C]	-20+85
Mechanical data		extraction force, maximum velocity and maximum acceleration see table page 13
Life expectancy		approx. 2 million full strokes (dependent on the displacement speed)
Weight	[g]	1300 - 1600, depending on the measurement range
Housing		aluminium, anodised, spring case PA6
Accessories		digital displays, deflection pulley, rope extensions, magnetic clamp (see pages 12 and 13)

^{*} other ranges on request

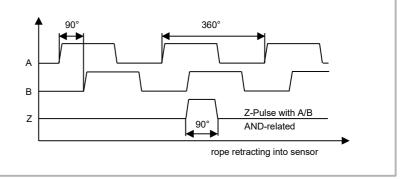
Electrical Data		Linedriver L	Push-Pull G		
		RS422 (TTL-compatible)			
Power supply +V	[VDC]	5, ±5 %	830		
Current consumption (no load)	[mA]	ty pical 40, max. 90	ty pical 40, max. 100		
Load/ Channel	[mA]	max. ±20	max. ±40		
Pulse frequency	[kHz]	max. 300	max. 200		
Signal level high	[V]	min. 2.5	min. +V – 3		
Signal level low	[V]	max. 0.5	max. 0.5		
Recommended circuit		Sensor Circuit +5 V A 0 V Z = 120 Ohm	Sensor Circuit A +V = 830 V R = 1 kOhm		

OUTPUT SIGNAL DIGITAL OUTPUT INCREMENTAL

Output signal

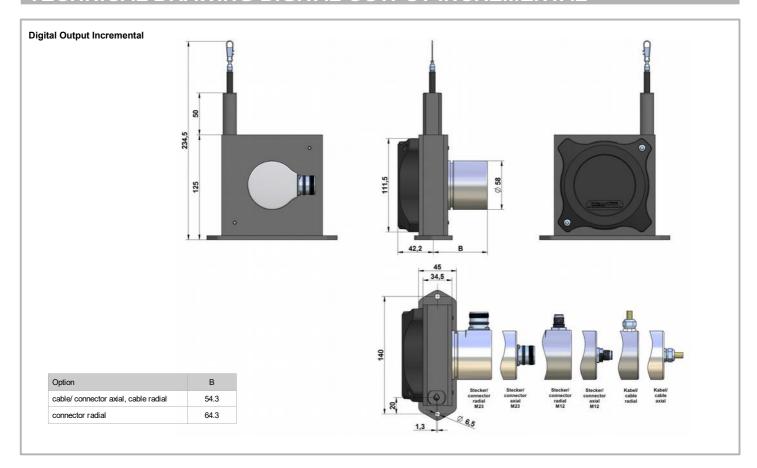
Pulses A and B are 90° phase-delayed (detection of direction). The Z-Pulse is emitted once per turn. The Z-Pulse distance is 317.68 mm (= circumference of the rope drum) and can be used as a reference mark.

Th diagram shows the signal without inverted signals; time line for return of rope.





TECHNICAL DRAWING DIGITAL OUTPUT INCREMENTAL



CONNECTION DIGITAL OUTPUT INCREMENTAL

Signal	0 V	+V	0 V *	+V *	Α	A _{Not}	В	B _{Not}	Z	Z _{Not}	screen
Connector M23, 12-pole	10	12	11	2	5	6	8	1	3	4	housing
Connector M12, 8-pole	1	2	-	-	3	4	5	6	7	8	housing
Cable output	white	brown	black	v iolet	green	y ellow	grey	pink	blue	red	housing

* For Linedriver L only. For long cable lengths it may occur that the operating voltage at the sensor does not suffice due to the output resistance. With the sensor lines 0 V_{sens} and $+V_{sens}$ the operating voltage can be checked and, if necessary, be readjusted at the input connection.

+V: Encoder power supply +VDC

0 V: Encoder power supply ground GND (0 V)

0 V_{sens} / + V_{sens} : Using the sensor outputs of the encoder, the voltage

present can be measured and if necessary increased accordingly

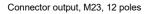
A, A_{Not}: Incremental output channel A

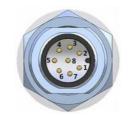
B, B_{Not}: Incremental output channel B

Z, Z_{Not}: Reference signal

Connector output







Connector output, M12, 8 poles

Cable output

Cable type PVC, flexible Cable direction radial or axial
Tadiai or ariai
Length 2.0 m
Diameter ø 4.5 mm
Wires 8 (push-pull) and 10 (linedriver) x 0.14 mm²
Temperature fixed installation -30+85 °C
flexible installation -20+85 °C
Assignment see table above



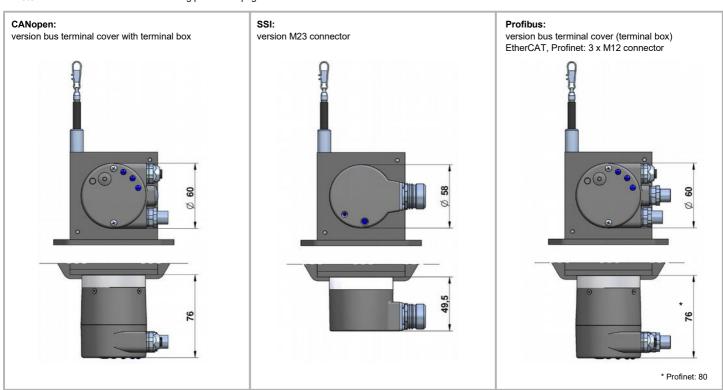
TECHNICAL DATA DIGITAL OUTPUT ABSOLUTE

		CANopen	SSI	Profibus-DP	EtherCAT	Profinet				
Measurement range	[mm]		3125 / 4000 / 5000							
Linearity	[%]	0.05, independent of the measurement range								
Resolution scalable (with Software)		y es	yes no yes yes							
Standard resolution	[Pulses/mm]	25,79	12,89	25,79	25,79	25,79				
	[Bit]	13	12	13	13	13				
Maximum resolution	[Pulses/mm]	206.3	-	206.3	206.3	206.3				
	[Bit]	16	-	16	16	16				
Sensor element		Multiturn-Absolute-Encoder (with optical code disk)								
Electrical connection		see order code page 16								
Power supply	[VDC]	1030 (reverse polarity protection of the power supply)								
Current consumption (no load, 24 V)	[mA]	max. 100	max. 50	max. 120	max. 120	max. 200				
Protection class				IP65, optional IP67						
Humidity			max. 9	90 % relative, no conder	sation					
Temperature	[°C]			-20+80						
Mechanical data		extra	ction force, maximum v	elocity and maximum a	cceleration see table pa	ige 14				
Life expectancy			approx. 2 million full s	trokes (dependent on the	e displacement speed)					
Weight	[g]			approx. 1100						
Housing			alumini	ium, anodised, spring ca	se PA6					
Special cables needed		y es	yes	yes	y es	y es				
Accessories		cable, connector,	digital display, deflectio	n pulley, rope extension	s, magnetic clamp (see	pages 12 and 13)				

Other encoder types are available on request

TECHNICAL DRAWING DIGITAL OUTPUT ABSOLUTE

Note: for dimensions of the sensor housing please see page 4.





DESCRIPTION CANopen

Parameters of the CAN	Parameters of the CANopen Interface									
Code	Binary									
Interface	CAN High-Speed acc. to ISO 11898, Basic- and Full-CAN, CAN Specification 2.0 B									
Protocol	CANopen profile DS406 V3.2 with manufacturer-specific add-ons									
Baud rate	10 1000 kbit/s (can be set via DIP switches/ Software configurable)									
Node address	1127 (can be set via rotary switches/ Software configurable)									
Termination switchable	can be set via DIP switches/ Software configurable									
SET Button (Option)	Zero or defined value option									
LED	LED is ON with the following fault conditions: Sensor error (internal code or LED error) too low voltage, over-temperature									





Electrical connection CANopen with 2 x M12 connectors, radial

	Bus OUT					Bus IN				
Signal	0 V + V CAN_L CAN_H CAN_GND					0 V	+ V	CAN_L	CAN_H	CAN_GND
PIN	3	2	5	4	1	3	2	5	4	1

Electrical connection CANopen with cable gland radial (removable bus terminal cover)

	Bus OUT						Bus IN				
Signal	CAN_GND CAN_L CAN_H 0 V +V					0 V	+V	CAN_L	CAN_H	CAN_GND	
Abbrev iation	CG	CL	СН	0 V	+V	0 V	+V	CL	СН	CG	

DESCRIPTION SSI

Parameters of the SSI interface	
Output driver	RS485 Transceiv er-ty pe
Permissible load/channel	max. ±20 mA
Signal level	HIGH: typ 3.8 V
	LOW: with I_{Load} = 20 mA typ 1.3 V
Resolution	12 bit
Code	Gray
SSI clock rate	ST-resolution: 50 kHz2 MHz
Monoflop time	≤ 15 µs
Data refresh rate	≤ 1 µs
Status and Parity bit	on request
Status and Parity bit	on request

SET Input (optional)	
Input	active HIGH
Input type	comparator
Signal level	HIGH: min 60% of +V, max. +V
(+V = power supply)	LOW: max. 25% of +V
Input current	<0.5 mA
Min. pulse duration (SET)	10 ms
Input delay	1 ms
New position data readable after	1 ms
Internal processing time	200 ms

Electrical connection SSI with cable output

		Cable (Isolate unused wires individually before initial start-up)											
Signal	0V	+V	C+	C-	D+	D-	SET	DIR	Status	n.c.	n.c.	n.c.	Н
Colour	white	brown	green	y ellow	gray	pink	blue	red	black	-	-	-	shield

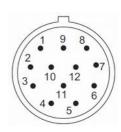
Electrical connection SSI with connector output M23, 12 pole

		M23 connector											
Signal	0V	+V	C+	C-	D+	D-	SET	DIR	Status	n.c.	n.c.	n.c.	Н
PIN	1	2	3	4	5	6	7	8	9	10	11	12	shield

+ V: Encoder power supply +VDC SET: SET Input

0 V: Encoder power supply GND (0 V) DIR: Direction input: If this input is active, output values are counted C+, C-: Clock signal backwards (decrease) when the shaft is turning clockwise.

D+, D-: Data signal H: Plug connector housing (Shield)





DESCRIPTION PROFIBUS DP

Parameters of the Profibus DP interface								
Code	Binary							
Interface	Profibus DP 2.0 Standard (DIN 19245 Part 3), RS485 Driver galvanically isolated							
Protocol	Profibus Encoder Profile V1.1 Class1 and Class2 with manufacturer-specific add-ons							
Baud rate	maximum 12 Mbit/s							
Device address	1127 (set by rotary switches)							
Termination switchable	set by DIP switches							
SET Button (Option)	Zero or defined value option							
LED	LED is ON with the following fault conditions: Sensor error, Profibus error							

Electrical connection Profibus with cable gland radial (removable bus terminal cover)

		Bus	s IN		Bus OUT				
Signal	B A 0 V +V				0 V	+V	В	Α	
Terminal	1	2	3	4	5	6	7	8	

The shield of the connection cable must be connected over a large area via the cable gland.

Electrical connection Profibus with connector output 3 x M12

Bus IN	Signal	-	PB_A	-	PB_B	shield	5
Dus III	PIN	1	2	3	4	5	3 × 4
Power	Signal	+V	-	0 V	-		2
supply	PIN	1	2	3	4		3 4
Bus OUT	Signal	BUS_VDC*	PB_A	BUS_GND*	PB_B	shield	1
Bus OUT	PIN	1	2	3	4	5	4 5

* For supplying an external Profibus termination resistor

Connection cables for connector output 3 x M12

cable end 1	cable end 2	cable order code		
Bus IN	open ends	K5P2M-B-M12-PROF		
	Bus OUT	K5P2M-SB-M12-PROF		
Bus OUT	open ends	K5P2M-S-M12-PROF		
Bus OUT	Bus IN	K5P2M-SB-M12-PROF		

Power supply	K4P2M-S-M12	
Terminator	M12-PROF-AW	

DESCRIPTION EtherCAT

Parameters of the Ether CAT Interface			
Code	Binary		
Protocol	EtherNet / EtherCAT		
Modes	Freerun, Distributed Clock		
Diagnostic LED red	LED is ON with the following fault conditions: Sensor error (internal code or LED error), low voltage, over-temperature		
Run LED green	LED is ON with the following conditions: Preop-, Safeop and Op-State (EtherCAT Status machine)		
2 x Link LEDs yellow	LED is ON with the following conditions (Port IN and Port OUT): Link detected		

Electrical connection EtherCAT with connector output 3 x M12

	Signal	Transmit data +	Receive data +	Transmit data -	Receive data -	1_2
Bus Port in	Abbrev iation	TxD+	RxD+	TxD-	RxD-	D coded
	PIN	1	2	3	4	4 3
Power	Signal	Voltage +	-	Voltage -	-	4 3
a ummh r	Abbrev iation	+V	-	0 V	-	
supply	PIN	1	2	3	4	1 2
	Signal	Transmit data +	Receive data +	Transmit data -	Receive data -	1_2
Bus Port out	Abbrev iation	TxD+	RxD+	TxD-	RxD-	D coded
	PIN	1	2	3	4	4 3



DESCRIPTION PROFINET

Parameters of the Profinet interface			
Code	Binary		
Protocol	PROFINET 10		
LED Link1/Link2	two coloured: green = active link		
	y ellow = data transfer		

Ezturn Software for Profinet (supplied with the encoder)

- Monitoring of cyclic data (e.g. position, speed)
- Monitoring of acyclic data (e.g. IMO, electronic name plate, encoder parameters, warnings and error messages, preset)
- Setting of preset values
- Firmware updates via the bus

Electrical connection Profinet with connector output 3 x M12

	Signal	Transmit data +	Receive data +	Transmit data -	Receive data -	1 2
Bus Port 1	Abbrev iation	TxD+	RxD+	TxD-	RxD-	D coded
	PIN	1	2	3	4	4 3
Power	Signal	Voltage +	-	Voltage -	-	4 3
a.ummlu	Abbrev iation	+V	-	0 V	-	
supply	PIN	1	2	3	4	1 2
	Signal	Transmit data +	Receive data +	Transmit data -	Receive data -	1_2
Bus Port 2	Abbrev iation	TxD+	RxD+	TxD-	RxD-	D coded
	PIN	1	2	3	4	4 3

General information about PROFINET IO

The PROFINET encoder implements the Encoder Profile 4.1. (according to the specification Encoder Version 4.1 Dec 2008").

It permits scaling and preset values, as well as many other additional parameters to be programmed via the PROFINET-Bus.

When switching on, all parameters are loaded from an EEPROM, where they were saved previously to protect them against power-failure, or taken over by the controller in the start-up phase.

Position, speed and many other states of the encoder can be transmitted.

PROFINET IO

The complete encoder profile according to Profile Encoder Version 4.1 as well as the Identification & Maintenance functionality Version 1.16 has been implemented. IM blocks 0, 1, 2, 3 and 4 are supported.

The Media Redundancy Protokoll is implemented here.

Basically, the advantage of MRP is that the functionality of the components, which are wired in a ring structure, is maintained in case of a failure or of a breakage of the wires in any location.



OPTIONS

The following table gives an overview of frequently used options, with which the standard sensors can be equipped. Please pay attention that not all options can be combined. You will find the not-combinable options on page 15 and 16 in the section of the product codes.

Option	Order code	Description		
Synthetic wire rope	COR	Synthetic wire rope, made out of abrasion resistant and enhanced Coramid.		
(instead of stainless steel wire rope)				
Protection class IP67	IP67	Use option IP67, if the sensor will operate in a humid environment.		
(instead of IP65)	0.	Note that with this option there may occur a light hysteresis in the output signal due to the special sealing		
(instead of 11 00)		The max. acceleration and displacement speed are reduced to 80 % of the specified value.		
Corrosion protection	CP			
Corrosion protection	OF .	Includes a V4A wire rope, stainless steel bearings and option M4. The sensors rope drum gets HARTCOAT®		
		coated. This coating is a hard-anodic oxidation that protects the sensor from corrosion by aggressive media		
In averaged accuracion must estima	ICP	(e. g. sea water) with a hard ceramics-like layer.		
Increased corrosion protection	ICP	Components of the housing and the rope drum get HARTCOAT® coated.		
only in combination with analog output	T40	Includes the options CP, IP67 and M4.		
Increased temperature range Low	140	Special components and a low temperature grease make a working temperature down to -40 °C		
only in combination with analog output	T120	(up to +85°C) possible.		
Increased temperature range High	1120	Sensors with potentiometer output (1R) and cable output can be operated from -20 to +120 °C when this		
only in combination with potentiometer 1R	C4 C2 C2	option is used. (NOT in combination with voltage-, current- or digital output signals)		
Changed rope outlet	S1, S2, S3	S1: rope outlet sideways at the top		
		S2*: rope outlet sideways at the bottom		
		S3*: rope outlet on the bottom		
		Rope outlet standard		
		* with modified mounting plate, see page 13		
Changed cable or	K1, K2, K3	Standard: sideways, opposite to the rope outlet K2 Cable/connector standard		
connector orientation		K1: at the top		
only for digital incremental output		K2: sideways, same side as the rope outlet		
and digital absolute output		K3: at the bottom		
		A		
		B -		
Rope fixation by M4 thread	M4	Optional, piv oted rope fixation		
		with screw thread M4, length 22 mm. rope clip with drill protection		
		Ideal for attachment to through holes (standard)		
		or thread holes M4.		
		optional M4 rope fixation		
		IVI4 TOPE IIXAUOTI		
Ring eye	RI	The end of the wire rope is equipped with a ring eye		
		instead of a rope clip.		
		Inside diameter 20 mm		
Inverted output signal	IN	The analog signal of the sensor is increasing by extracting		
only in combination with analog output		the rope (standard). Option IN inverts the signal, i. e. the		
		signal of the sensor declines by extracting the rope.		
		, inverted		
		0V/4mA standard range		
		▼ 0 FS		

ACCESSORIES

Deflection pulley - UR2

The rope must be extracted from the sensor vertically. The maximum variation from the vertical is 3°. A deflection pulley allows a change in the direction of the wire rope. Several pulleys may be used. The rope clip must not be guided over the deflection pulley.

Material foot: anodised aluminium POM-C

Material

rope wheel: by 2 hexagon socket or countersunk screws M6, Mounting:

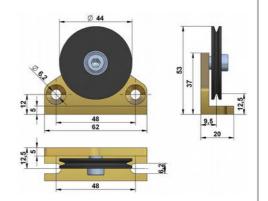
vertical or horizontal mounting possible.

Ball bearings: with special low temperature grease and

RS-sealing.

Temperature: -40...+80 °C.



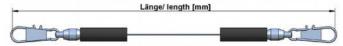


Rope extension - SV

For bridging a greater distance between the measuring target and the sensor a rope extension can be applied. The rope clip must not be guided over the deflection pulley.

Please specify the length needed in your order (XXXX). The minimum length is 150 mm:

SV1-XXXX: rope extension (150...4995 mm) SV2-XXXX: rope extension (5000...19995 mm) SV3-XXXX: rope extension (20000...40000 mm)

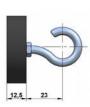


Magnetic clamp - MGG1

Use the magnetic clamp to quickly attach the rope to metallic objects without any assembly time. A rubber coating provides gentle contact (e. g. on varnished surfaces) and prevents from slipping due to vibration.

The magnet consists of a neodym core for an increased adhesive force of 260 N. The hook makes it easy to attach the rope clip.





ACCESSORIES ANALOG OUTPUT

Cable with connector M12, 4 poles, shielded					
K4P2M-S-N	M12 2	m, connecto	or straight		
K4P5M-S-N	M12 5	5 m, connector straight			
K4P10M-S	-M12 1	0 m, connect	or straight		
K4P2M-SV	/-M12 2	2 m, connector angular			
K4P5M-SV	/-M12 5	5 m, connector angular			
K4P10M-S	W-M12 1	0 m, connect	or angular		
PIN No.	cable colour	PIN No.	cable colour		
Pin 1	brown	Pin 3	blue		
Pin 2	white	Pin 4	black		





Mating Connector	r M12, 4 poles, shielded
D4-G-M12-S	straight, M12 for self assembly
D4-W-M12-S	angular, M12 for self assembly
	protection class: IP67
	temperature: -25+90 °C
	cable passage: ø 48 mm
	wire cross-section: 0.140.34 mm²
	mode of connection: spring cage

Digital display - PAXD (for Potentiometer)

Use the PAXD display to visualise the measured distance of the position transducer with a potentiometer as sensor element. A transmission of the measurement data to a computer or PLC can be done with interface plug-in cards.

Potentiometer signal Inputs:

Analog output (plug-in cards): 0...20 mA, 4...20 mA, 0...10 V

RS485, RS232, DeviceNet, USB, Profibus, Relay output, Transistor output Serial interfaces (plug-in cards):

IP65 (Front panel) Protection class:

Display: 5 digits

PAXD000B: 1 channel, power supply: 85 to 250 VAC PAXD001B: 1 channel, power supply:: 11 to 36 VDC/24 VAC

For further information please see the data sheet of the PAXD display series





ACCESSORIES ANALOG OUTPUT

Digital displays PAXP (1 channel) and PAXDP (2 channels) for sensors with analog output signals 0..10V or 4..20 mA

Use the PAXD or PAXDP display to visualise the measured distance of transducers with an analog output signal. A transmission of the measurement data to a computer or PLC can be done with interface plug-in cards.

Inputs: 0...10 V or 4...20 mA, 2 independent counters (for PAXDP)

Analog output (plug-in cards): 0...20 mA, 4...20 mA, 0...10 V

Serial interfaces (plug-in cards): RS485, RS232, DeviceNet, USB, Profibus, Relay output, Transistor output

Protection class: IP65 (front panel)

Display: 5 digits

PAXP000B: 1 channel, power supply: 85 to 250 VAC
PAXP001B: 1 channel, power supply: 11 to 36 VDC/24 VAC
PAXDP000B: 2 channels, power supply: 85 to 250 VAC

PAXDP001B: 2 channels, power supply: 11 to 36 VDC/24 VACC

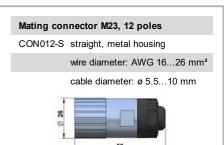


For further information please see the PAXD and PAXDP data sheet.

ACCESSORIES DIGITAL OUTPUT INCREMENTAL

Cable with connector	M12, 8 poles, shielded
K8P2M-S-M12	2 m, connector straight
K8P5M-S-M12	5 m, connector straight
K8P10M-S-M12	10 m, connector straight
K8P2M-SW-M12	2 m, connector angular
K8P5M-SW-M12	5 m, connector angular

Mating connector M12, 8 poles, shielded			
D8-G-M12-S	mating connector straight		
D8-W-M12-S	mating connector angular		
	protection class: IP67		
	temperature: -25+90 °C		
	cable passage: ø 48 mm		



CON012-S

Digital distance and speed display - WAY-D for incremental output signals

Use the WAY-D display to visualise the measured distance or the speed (tachometer) of the position transducer. A transfer of data to a PC or PLC can be done with the RS232 interface of the WAY-DR.

Protection class: IP65 (front panel)
Display: 6 digits
Supply: 115 / 250 VAC

Output Linedriver L (TTL, RS422):

WAY-DS-5VH: display only, input level TTL

WAY-DG-5VH: display with two presets and switching outputs, input level TTL WAY-DR-5VH: display with serial interface RS232 / RS485, input level TTL

Output Push-Pull G:

WAY-DS: display only, input level HTL

WAY-DG: display with two presets and switching outputs, input level HTL WAY-DR: display with serial interface RS232 / RS485, input level HTL



For further information please see the WAY-D data sheet.

ACCESSORIES DIGITAL OUTPUT ABSOLUTE SSI

Digital distance and speed display - WAY-SSI for SSI output signals

Use the WAY-SSI display to visualise the measured distance or the speed (tachometer) of the position transducer. A transfer of data to a PC or PLC can be done with the RS232 interface of the WAY-SSI-R.

Protection class: IP65 (front panel)
Display: 6 digits
Supply: 115 / 250 VAC
WAY-SSI-S: display only

WAY-SSI-A: display with analog output

WAY-SSI-G: display with two presets and switching outputs WAY-SSI-R: display with serial interface RS232 / RS485



For further information please see the WAY-SSI data sheet.



MECHANICAL DATA

Measurement Range [mm]	Extraction Force F _{min} [N]	Extraction Force F _{max} [N]	Speed V _{max} [m/s] *	Acceleration a [m/s²] *
3125	8.0	10.0	10	140
4000	8.0	11.0	10	140
5000	8.0	11.6	10	140

^{*} reduced to 80 % when option IP67 is used

INSTALLATION

 Mount the sensor at the designated place by using the fixing holes before extracting the rope and before attaching the rope to the measuring target.

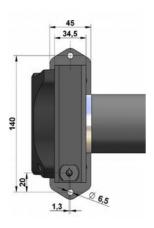


- Open the rope clip after the sensor is fully mounted and extract the measuring rope. Hook the rope clip on the measuring object and close the bracket of the clip. For safety reasons put a screw driver trough the clip to extract the rope.
- Check the track of the measuring target on collision with the sensor housing and on exceeding the specified measurement range. When installing the sensor make sure
 that the rubber stopper does not touch the rope outlet.
- Connect the electronics according to the sensor type. When laying the cables be careful not to under-run the minimal allowed bending radius of the cable (5 x cable diameter).
- The rope must be extracted from the sensor vertically. The maximum variation from the vertical is 3°. Avoid carefully extracting the rope at an inclination, since the durability of the instrument would shorten considerably. If it is not possible to keep the limit of 3°, a deflection pulley has to be used.
- · The measuring range begins after approximately 2 mm extracted rope (=zero point). The mechanical reserve at the end of the measuring range is about 20 mm.
- When mounting outdoors protect the sensor and the rope from icing at temperatures below 0 $^{\circ}$ C.
- · Guide the rope preferably in corners or guarded in channels to prevent pollution or accidental touch.
- When operating the sensor, take care **not to let the rope snap back** by mistake or extract the rope **over the specified measurement range**, as this might destroy the sensor.
- Maintenance: These instruments are maintenance-free. If however, the rope is soiled due to adverse environmental conditions, it can be cleaned with a cloth drenched in resin-free machine oil.

Mounting: standard rope outlet, rope outlet sideways top (S1)

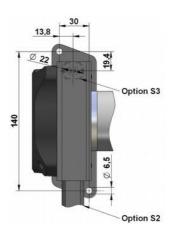
The sensor is usually installed by using the regular mounting plate (see technical drawing on page 4).

By disassembling the mounting plate, there are 2 x M4 threads in the sensor housing for alternative installation.



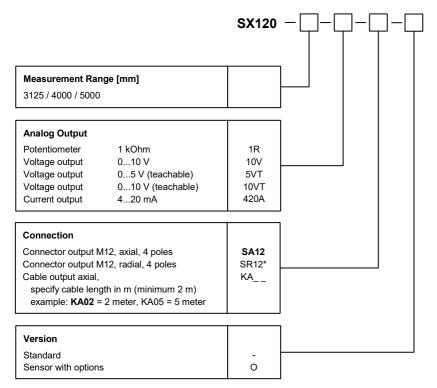
Mounting: rope outlet sideways bottom (S2), rope outlet bottom (S3)

Sensors with option rope outlet S2 and S3 have a modified base plate.





ORDER CODE ANALOG OUTPUT

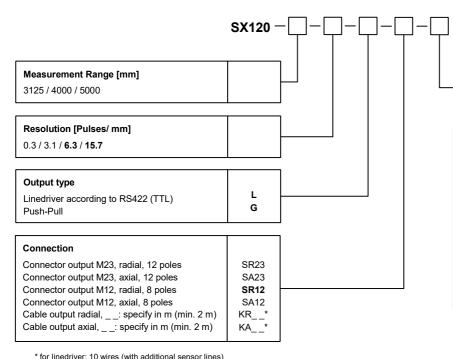


Option	Description
M4	rope fixation M4 thread
COR	synthetic wire rope, made out of Coramid
RI	ring eye (instead of rope clip)
S1	rope outlet sideways top
S2	rope outlet sideways bottom
S3	rope outlet bottom
IN	inverted output signal
L05	improved linearity 0.05 %
T40	increased temperature range low -40+85°C
T120	increased temperature range high -20+120 °C
IP67	protection class IP67
CP	corrosion protection SX120
ICP	increased corrosion protection SX120
1	

Option	not combinable with
M4	CP, ICP
RI	CP, ICP
T40	L05
T120	IP67, COR, CP, ICP, 10V, 420A, SA12, SR12
IP67	TEMP120, ICP
CP	M4, RI
ICP	IP67, M4, RI

Bold text: standard with shorter lead time

ORDER CODE DIGITAL OUTPUT INCREMENTAL



ioi illieulivei.	10 WILES (WILLI AUGILIONAL SENSOL IIIIES)
for push-pull:	8 wires (without sensor lines)

Bold text: standard with shorter lead time

Option	Description
M4	rope fixation M4 thread
COR	synthetic wire rope, made out of Coramid
RI	ring eye (instead of rope clip)
S1	rope outlet sideways top
S2	rope outlet sideways bottom
S3	rope outlet bottom
K1	cable/connector orientation top
K2	cable/connector orientation left
K3	cable/connector orientation bottom
L02	improved linearity 0.02 %
IP67	protection class IP67
CP	corrosion protection SX120

0

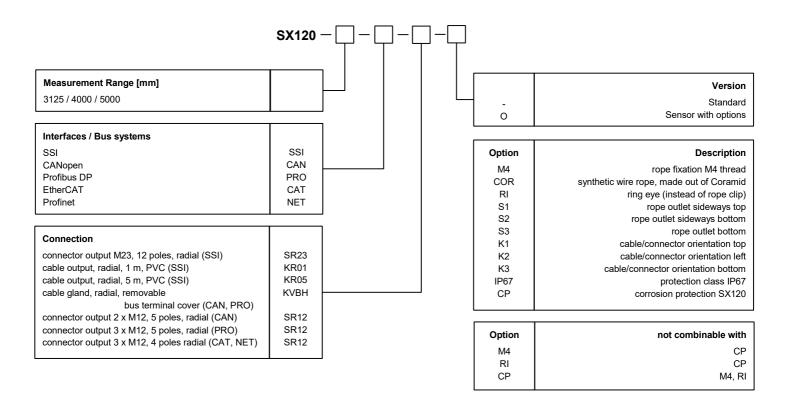
Version

Standard Sensor with options

	Option	not combinable with
	M4	CP
	RI	CP
	L02	resolutions 0.3 / 3.1
	CP	M4, RI
ı		



ORDER CODE DIGITAL OUTPUT ABSOLUTE



GENERAL ACCESSORIES

SQUEEZER2M	2 m cable	SV1-XXXX	rope extension (1504995 mm)
SQUEEZER5M	5 m cable	SV2-XXXX	rope extension (500019995 mm)
SQUEEZER10M	10 m cable	SV3-XXXX	rope extension (2000040000 mm)
UR2	deflection pulley		
MGG1	magnetic clamp		

ACCESSORIES ANALOG OUTPUT

Cable with mating connector M12, 4 poles, shielded		Digital display 1 channel, 010V/420 mA	
K4P2M-S-M12	2 m, straight connector	PAXP000B	1 channel, supply: 85 to 250 VAC
K4P5M-S-M12	5 m, straight connector	PAXP001B	1 channel, supply: 1136 VDC/24 VAC
K4P10M-S-M12	10 m, straight connector		
K4P2M-SW-M12	2 m, angular connector	Digital display	2 channels, 010V/420 mA
K4P5M-SW-M12	5 m, angular connector	PAXDP00B	2 channels, supply: 85 to 250 VAC
K4P10M-SW-M12	10 m, angular connector	PAXDP01B	2 channels, supply: 1136 VDC/24 VAC
Mating Connector M12, 4 poles, shielded		Digital display 1 channel, Potentiometer	
D4-G-M12-S	straight, M12 for self assembly	PAXD000B	1 channel, supply: 85 to 250 VAC
D4-W-M12-S	angular, M12 for self assembly	PAXD001B	1 channel, supply: 1136 VDC/24 VAC
Connection cable Sensor - Squeezer			
K4P1,5M-SB-M12	1.5 m, 4-pole, shielded		



ACCESSORIES DIGITAL OUTPUT INCREMENTAL

Cable with mating connector M12, 8 poles, shielded		
K8P2M-S-M12	2 m, straight connector	
K8P5M-S-M12	5 m, straight connector	
K8P10M-S-M12	10 m, straight connector	
K8P2M-SW-M12	2 m, angular connector	
K8P5M-SW-M12	5 m, angular connector	
K8P10M-SW-M12	10 m, angular connector	

Cable with mating connector M23, 12 poles, shielded K8P2M-S-M23 2 m, straight connector

K8P5M-S-M23 5 m, straight connector K8P10M-S-M23 10 m, straight connector

Mating Connector M23, 12 poles, shielded

CON012-S straight, M23 for self assembly, metal housing Mating Connector M12, 8 poles, shielded D8-G-M12-S straight, M12 for self assembly D8-W-M12-S angular, M12 for self assembly

Digital display 1 channel, Linedriver L (input level TTL, RS422)

WAY-DS-5VH display only

WAY-DG-5VH display with two presets and switching outputs

WAY-DR-5VH display with serial interface RS232 / RS485

Digital display 1 channel, Push-Pull G

WAY-DS display only WAY-DG display with two presets and switching outputs WAY-DR

display with serial interface RS232 / RS485

CCESSORIES DIGITAL OUTPUT ABSOLUTE

SSI output:		
K12P02M-S-M23-SSI	2 m cable, shielded, M23 connector straight	
K12P05M-S-M23-SSI	5 m cable, shielded, M23 connector straight	
K12P10M-S-M23-SSI	10 m cable, shielded, M23 connector straight	
K12P15M-S-M23-SSI	15 m cable, shielded, M23 connector straight	
CON012-S	Mating connector M23 shielded, straight, 12 poles	
Digital display 1 channel, for sensors with SSI signal		
WAY-SSI-S	display only	
WAY-SSI-A	display with analog output	
WAY-SSI-G	display with two presets and switching outputs	
WAY-SSI-R	display with serial interface RS232 / RS485	

K5P2M-B-M12-PROF 2 m cable, plug female M12, 5 poles, open ends

K5P2M-SB-M12-PROF 2 m cable, connector male M12, 5 poles, plug female M12

K5P2M-S-M12-PROF 2 m cable, connector male, M12, 5 poles, open ends

M12-PROF-AW terminator

Profibus DP:

CANopen output: K5P2M-B-M12-CAN 2 m cable, plug female M12, 5 poles, open ends K5P2M-SB-M12-CAN 2 m cable, connector male M12, 5 poles, plug female M12 K5P2M-S-M12-CAN 2 m cable, connector male, M12, 5 poles, open ends

EtherCAT / Profinet:

K4P2M-S-M12-CAT 2 m cable, connector male M12, 4 poles, open ends K4P5M-S-M12-CAT 5 m cable, connector male M12, 4 poles, open ends K4P10M-S-M12-CAT 10 m cable, connector male M12, 4 poles, open ends K4P2M-SS-M12-CAT 2 m cable, connector male M12 on both ends, 4 poles K4P5M-SS-M12-CAT 5 m cable, connector male M12 on both ends, 4 poles K4P10M-SS-M12-CAT 10 m cable, connector male M12 on both ends, 4 poles

Subject to change without prior notice.

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